



Automated Probabilistic Finite Element Model Calibration Tool Based on Uncertainty Quantification and Machine Learning

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Background:

- Metallic additive manufacturing (AM) → Laser Powder Bed Fusion (LPBF)
- Laser produced melt pools ($\sim \mu\text{m}$) to build parts ($\sim \text{cm}$) with millions of scan passes
 - Local variation of defects and microstructure [1, 2] = variation and inconsistencies in part properties
 - Each part printed with a unique set of material properties → qualification and certification (Q&C)

NASA Transformational Tools and Technologies Project (TTT):

- Predict properties and quantify variability to ease hurdles to Q&C [3]
 - High fidelity simulations are very time costly ($\sim 100\text{k}$ CPU hours) and still require calibration [4]
 - High-temperature material properties
 - Probabilistically calibrate and validate reduced fidelity thermal finite element (FE) model (COMSOL®)

Extract measured data (10 scans) → Calibrate FE Model at each scan → Interpolate between scans

[1] Mahadevan, Sankaran, Paromita Nath, and Zhen Hu. "Uncertainty Quantification for Additive Manufacturing Process Improvement: Recent Advances." ASCE-ASME Journal of Risk and Uncertainty in Engineering Systems, Part B: Mechanical Engineering 8.1 (2022): 010801.

[2] Herriott, Carl, et al. "A multi-scale, multi-physics modeling framework to predict spatial variation of properties in additive-manufactured metals." Modelling and Simulation in Materials Science and Engineering 27.2 (2019): 025009.

[3] Blakey-Milner, Byron, et al. "Metal additive manufacturing in aerospace: A review." Materials & Design 209 (2021): 110008.

[4] Khairallah, S., Anderson, A., Rubenchik, A., et. al., 2016, "Laser powder-bed fusion additive manufacturing: Physics of complex melt flow and formation mechanisms of pores, spatter, and denudation zones," Acta Materialia, Vol. 108, p. 36-45.

Materials and Test Matrix

Single scan passes on bare Ti-6Al-4V plate:

- EOS M290 LPBF machine at University of Pittsburgh
- Pads each contain scans 1 – 10 (each scan repeats 3 times)
- Process parameters (PPs): laser power and velocity
- 10 scans: 30 serial cross sections → 300 total images

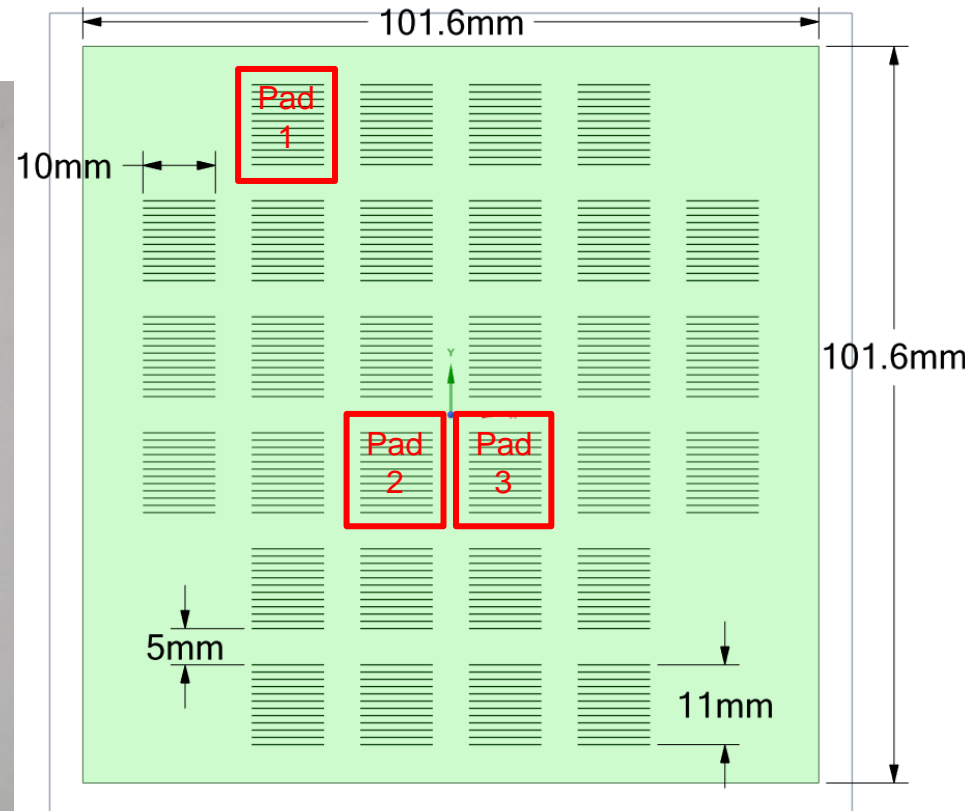
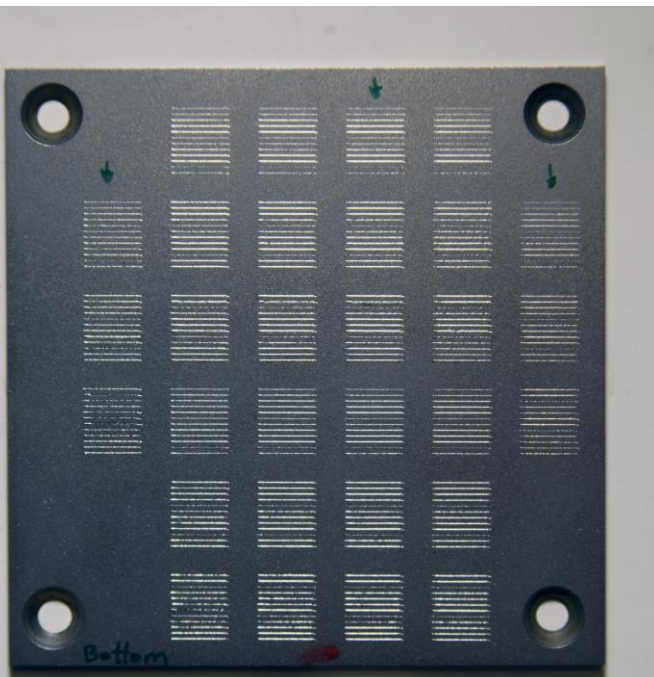
Test Matrix

Scan Number	Power (W)	Velocity (mm/s)
1	225	1250
2	225	1500
3	170	750
4	170	1000
5	170	1250
6	170	1500
7	150	750
8	150	1000
9	150	1250
10	150	1500

EOS M290 default setting.
Used to validate interpolator.

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Plate Top Surface

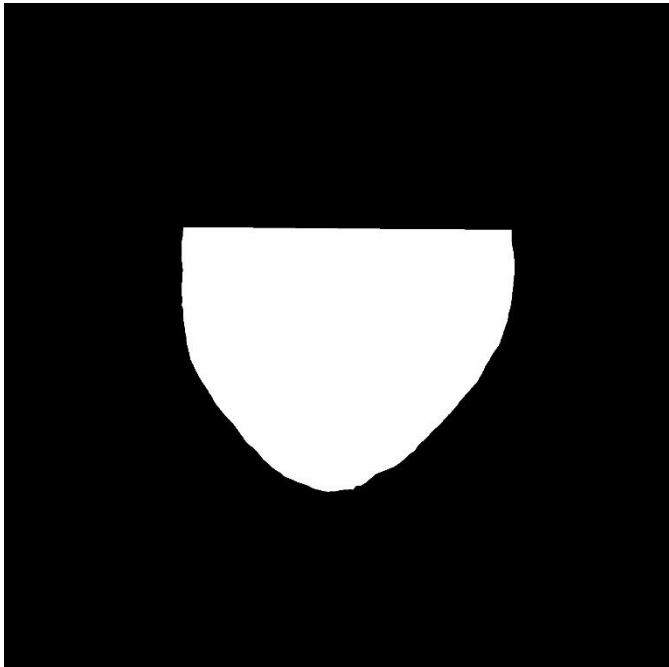


Melt Pool Contour Identification Approach

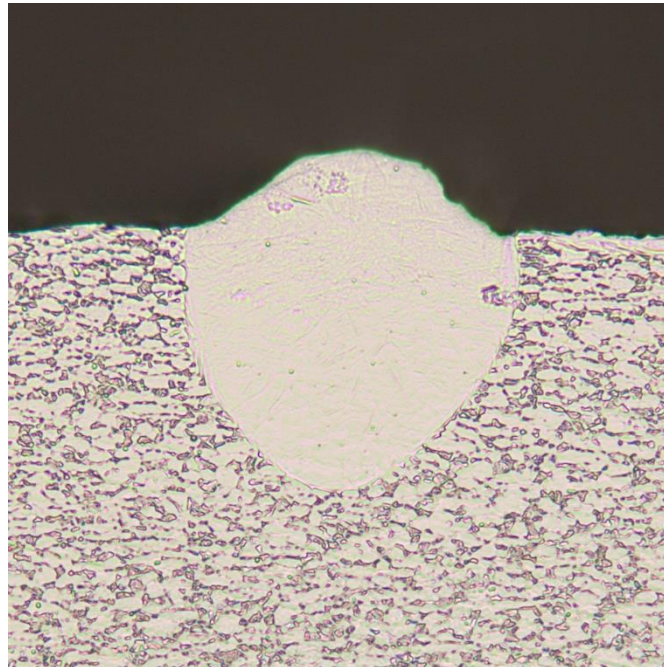
Extract measured data (10 scans) → Calibrate FE Model at each scan → Interpolate between scans

- Required to process large number of images (300 current; thousands in future)
- U-Net architecture (Convolutional Neural Network (CNN))
 - Implemented in Python (TensorFlow) using EfficientNetB3 pretrained image classification model
- Semantic segmentation of an input image into two parts: melt pool and other
- Extrema to identify melt pool dimensions (MPDs): width and depth

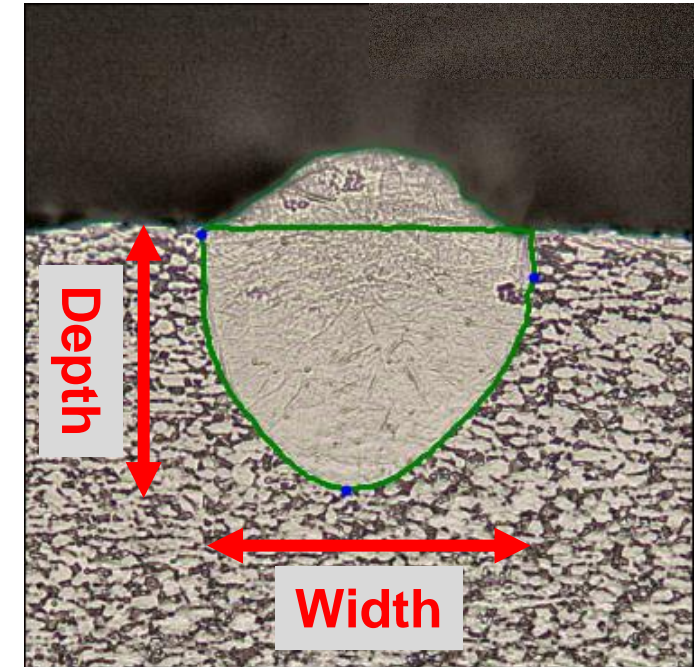
Training Mask



Input Image



CNN Predicted Contour



Melt Pool Contour Identification Results

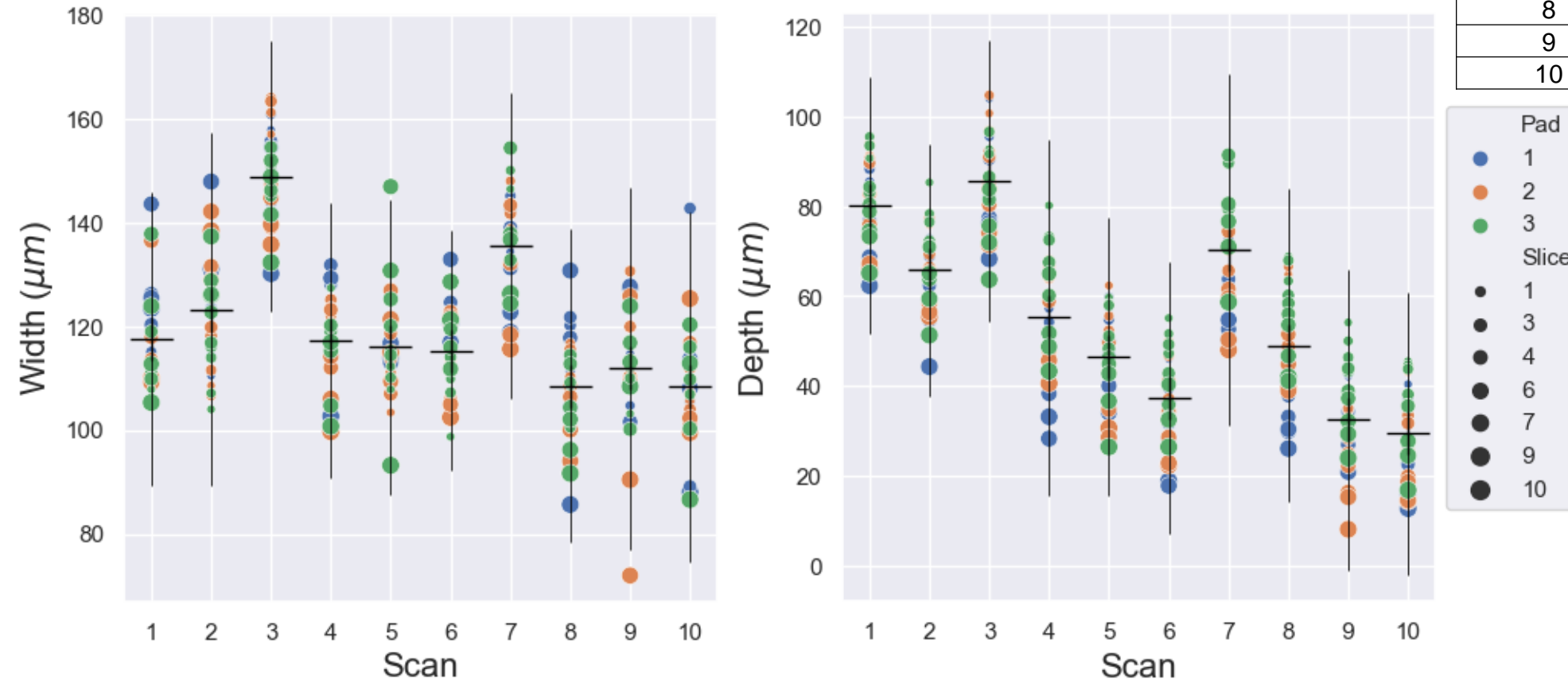
CNN prediction results:

- CNN test set (9 images): average accuracy 95.2% (intersection over union)

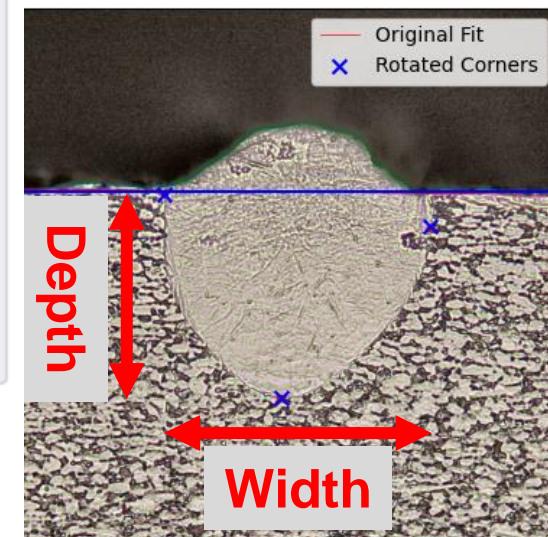
Scan Number	Power (W)	Velocity (mm/s)
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5	170	1250
6	170	1500
7	150	750
8	150	1000
9	150	1250
10	150	1500

Melt Pool Width and Depth for all 300 Images

Error bars show +/- 3x Standard Deviation and Mean



Contour Reduction





Probabilistic Calibration Approach

Extract measured data (10 scans) → Calibrate FE Model at each scan → Interpolate between scans

Probabilistic calibration of FE model to experimental observations:

- Predict MPDs by tuning FE model heat source parameters at each PP setpoint

Active learning loop



FE Model: Calibrate Volumetric Heat Source

Reduced order FE transient thermal model physics:

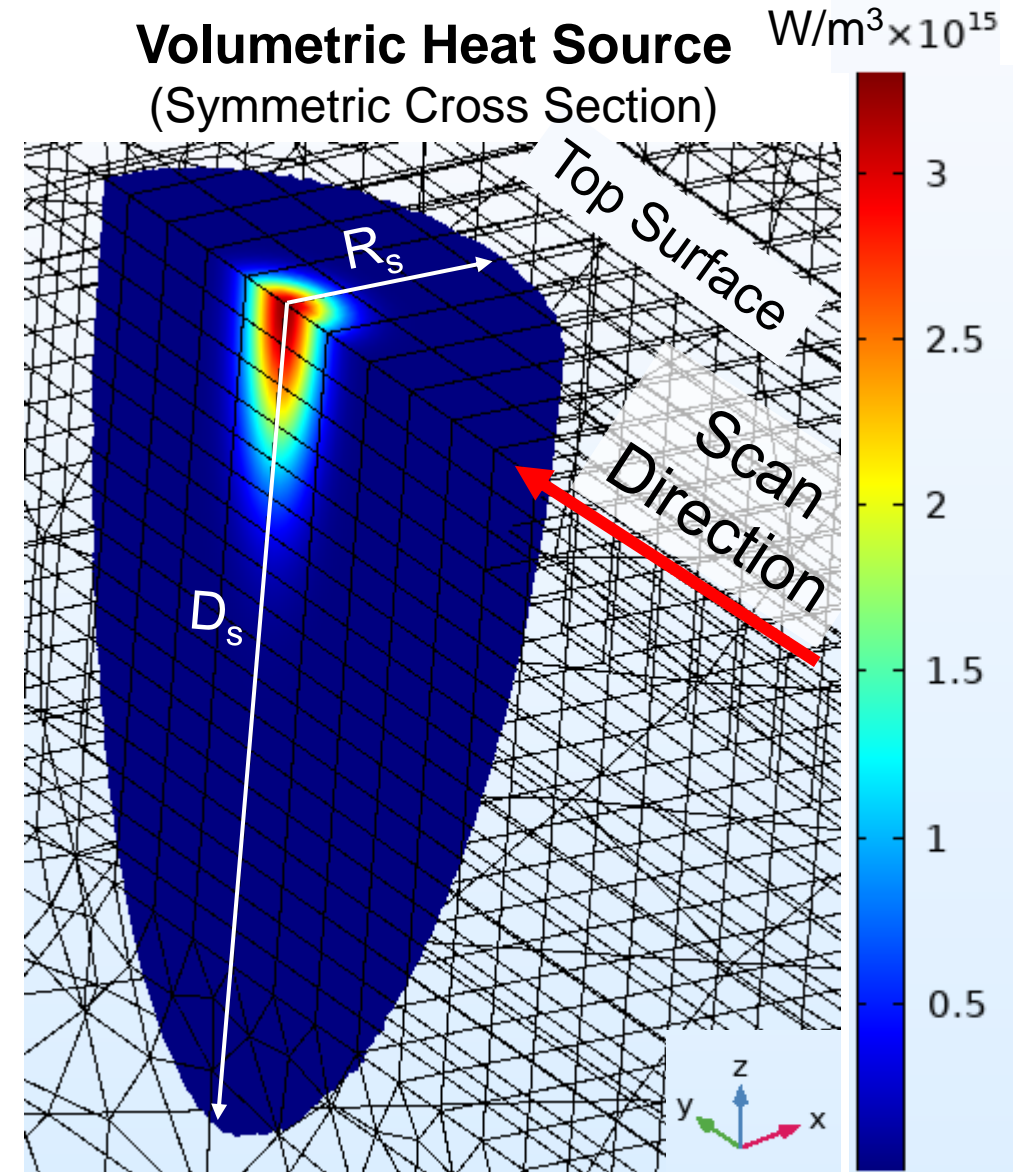
- Volume:
 - Heat diffusion
 - Liquid – solid phase change
 - Volumetric laser heat source (Gaussian, based on Goldak [5])
- Surface:
 - Radiation and convection heat loss
 - Liquid – gas evaporation heat loss
- Ignores expensive and uncertain melt pool physics

Volumetric heat source calibration variables:

- R_s : heat source radius
- D_s : heat source depth
- a_{eff} : effective laser power absorptivity

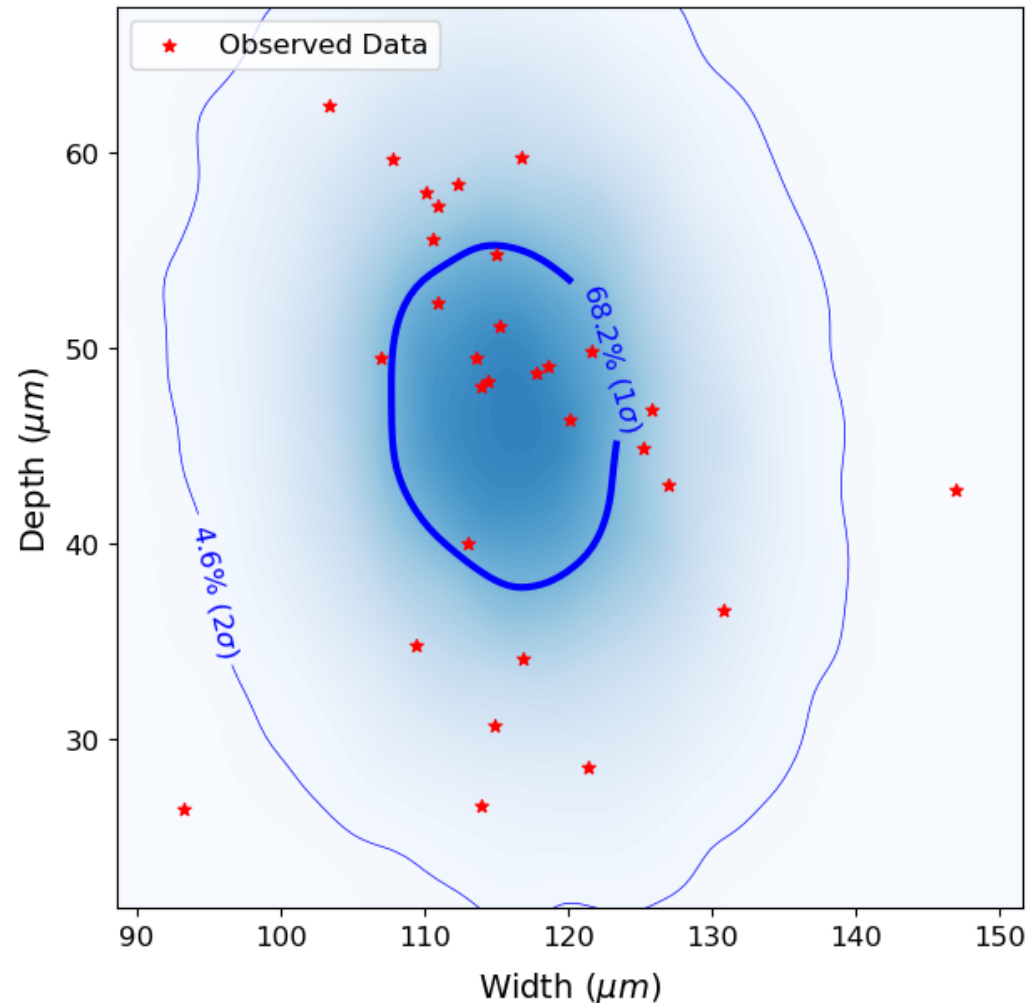
Predicted output variables (MPDs):

- Width
- Depth

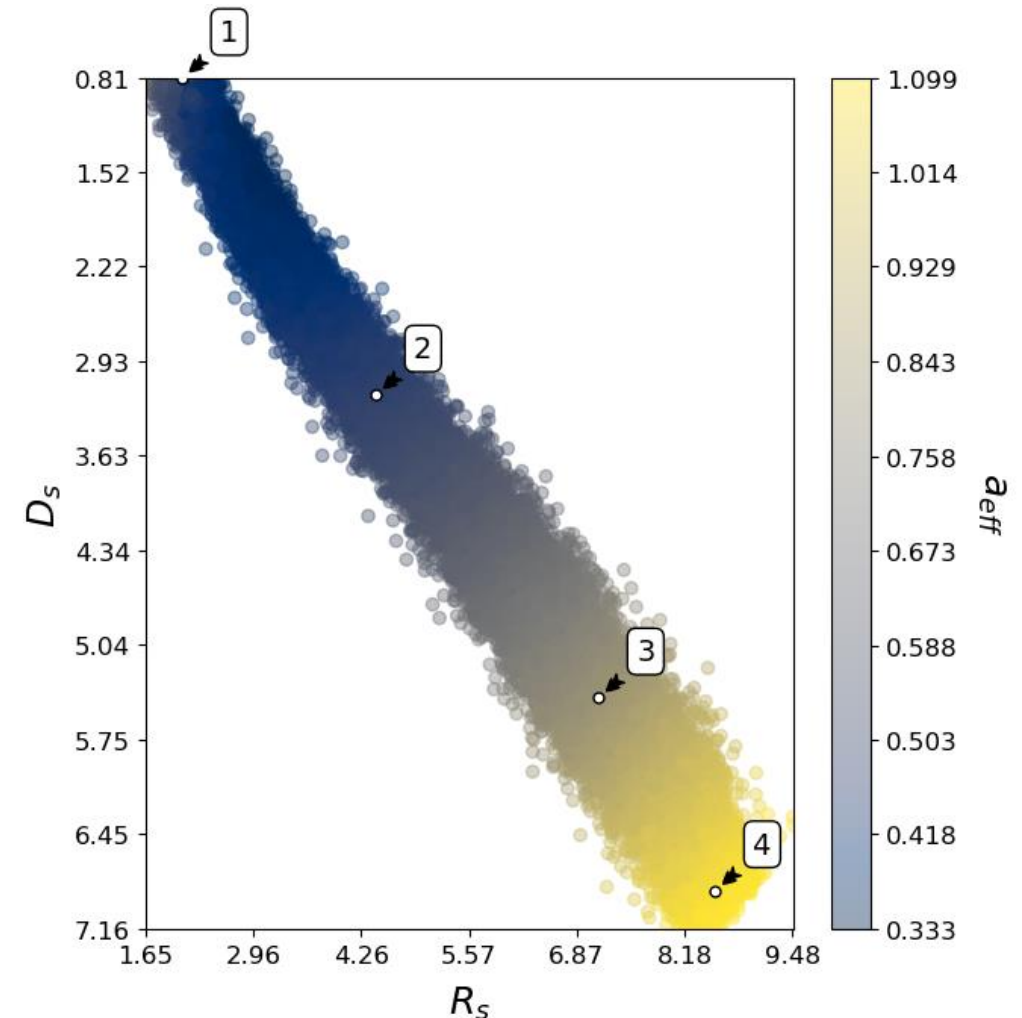


FE Model Calibration Results (Scan 5)

Surrogate predicted melt pool dimensions for posterior



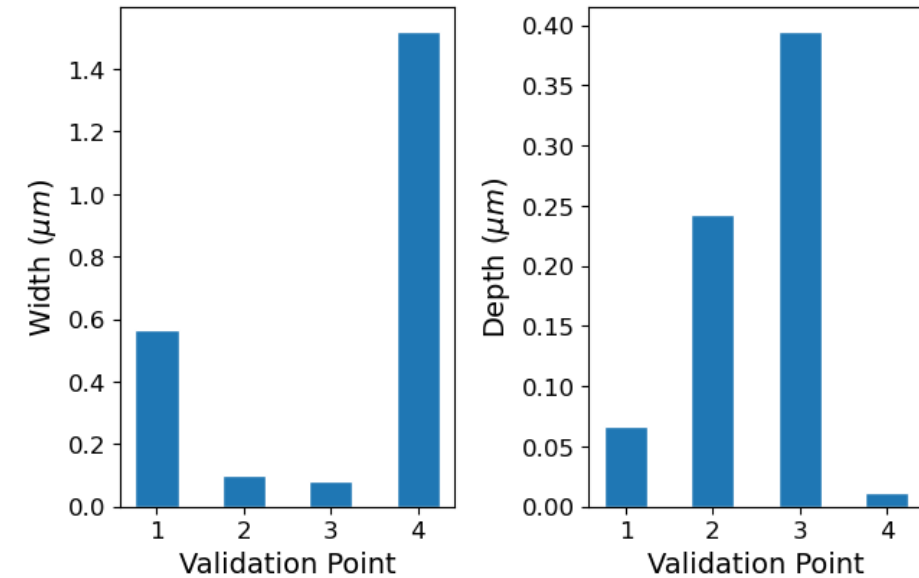
Posterior: distribution of calibrated heat source parameters and 4 selected validation points





Validation of FE Model Calibration Results (Scan 5)

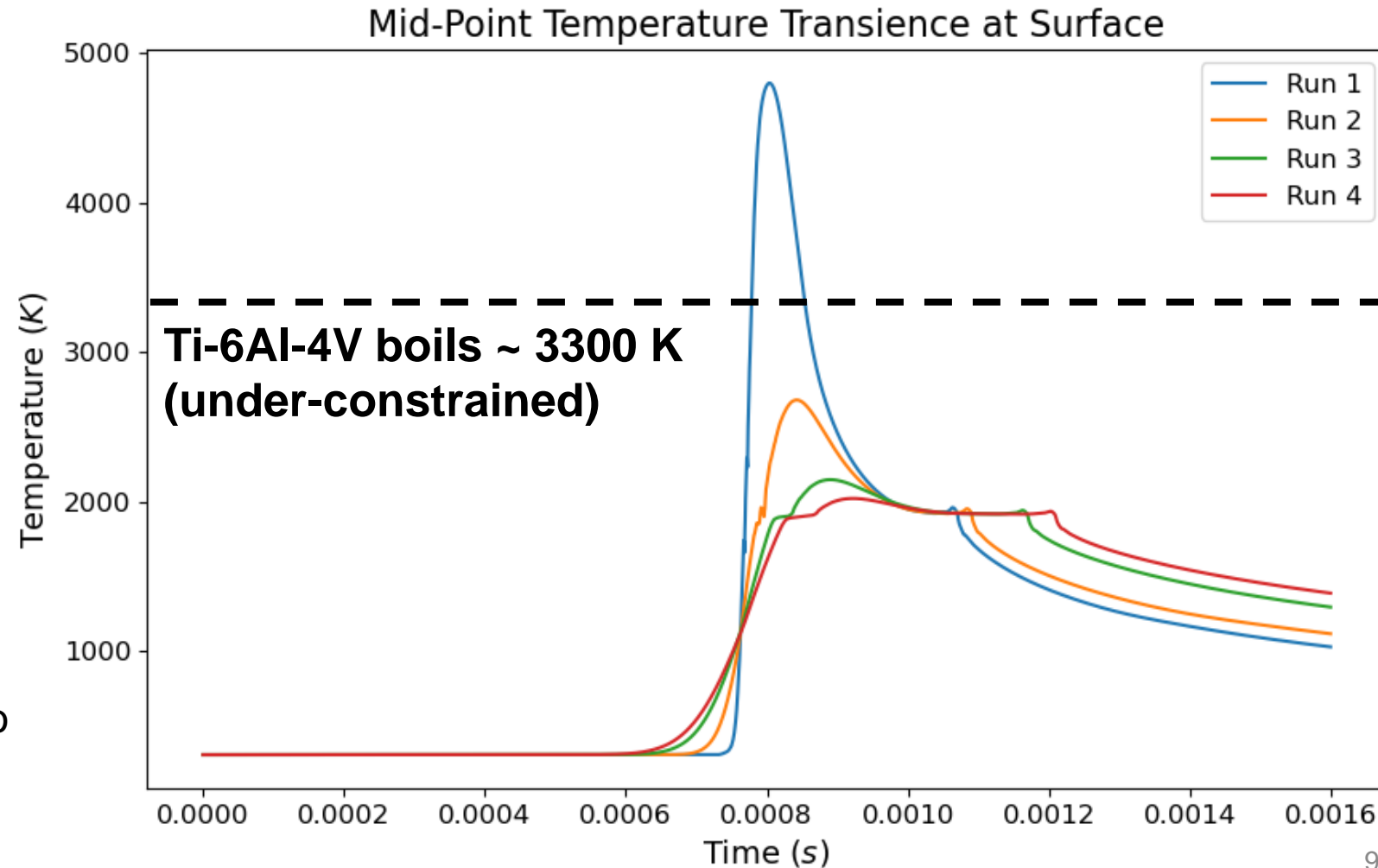
Surrogate validation: Absolute error at 4 validation points



Calibration approach is under-constrained:

- Subset of scan 5 posterior will be used to fit interpolator targeting 3300 K temperature maximum

Temperature history at 4 selected validation points





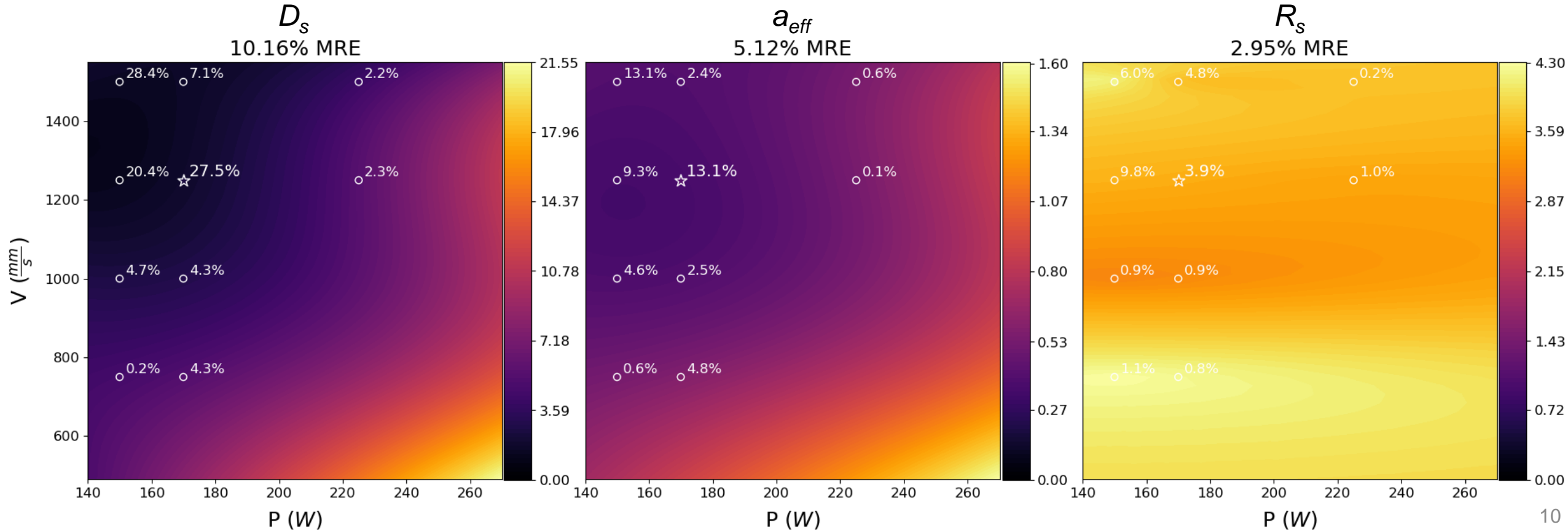
Interpolator: Optimize Fit of Single Points

Extract measured data (10 scans) → Calibrate FE Model at each scan → Interpolate between scans

Gaussian Process Regression optimized using custom grid search:

- Separate estimators optimized for each variable (D_s , a_{eff} , R_s) at median posterior point
- “Leave one out” k-folds cross validation for 9 of 10 points; scan 5 reserved (validation point)

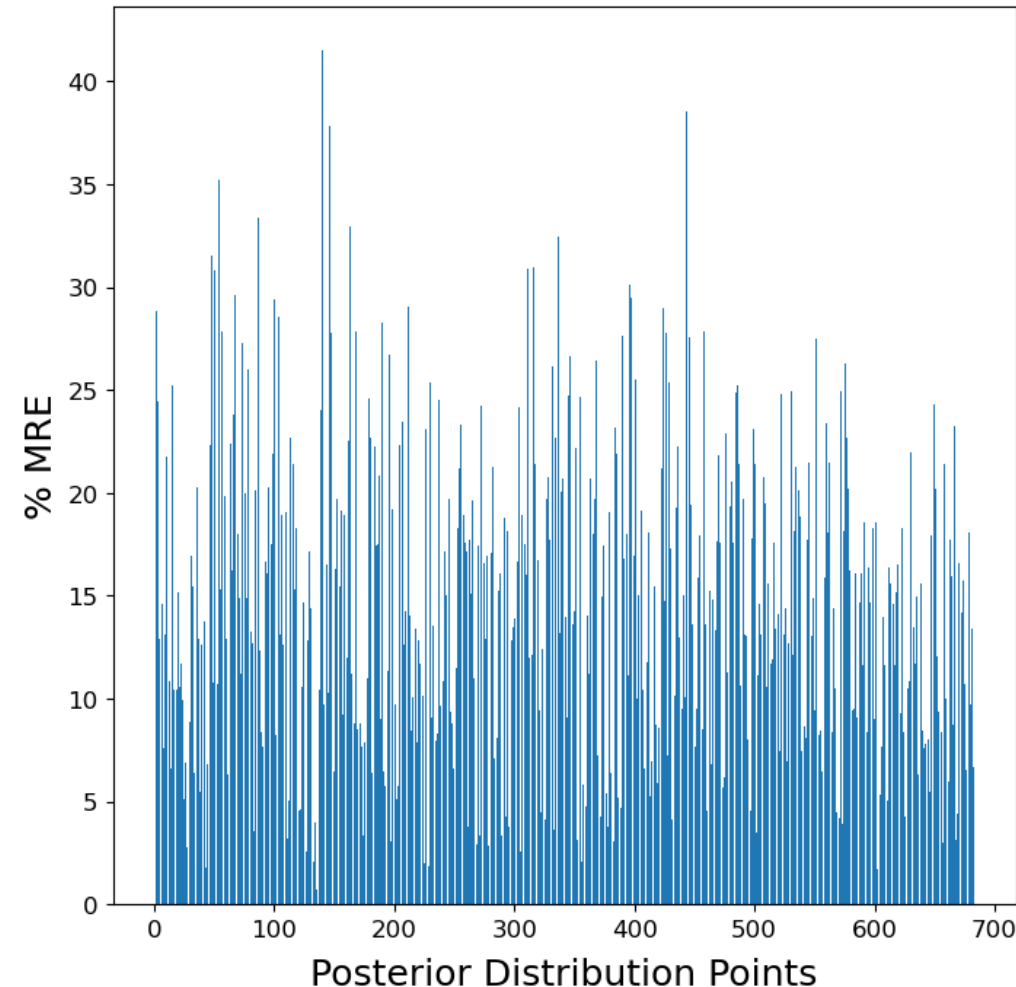
Mean Relative Error (MRE) for fit of most probable points; star indicates validation point (scan 5)



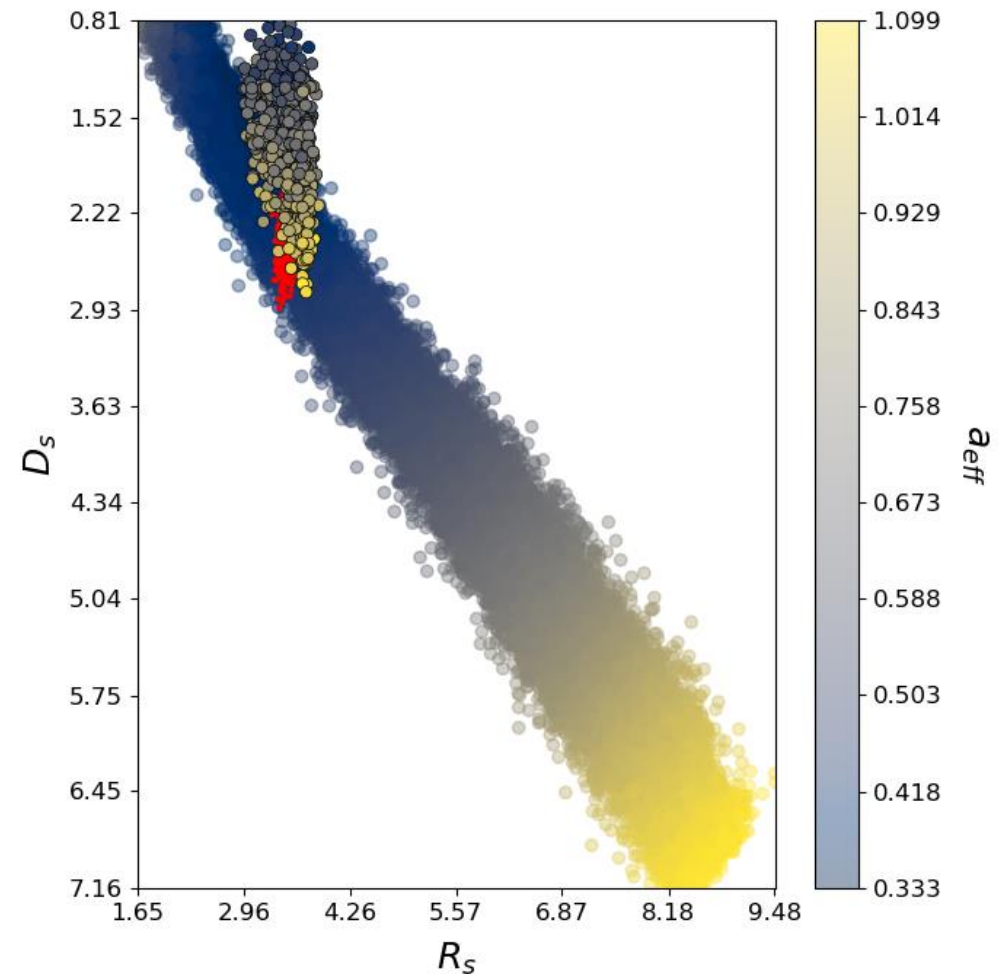
Interpolator Validation: Ensemble of Fits Estimate Distribution



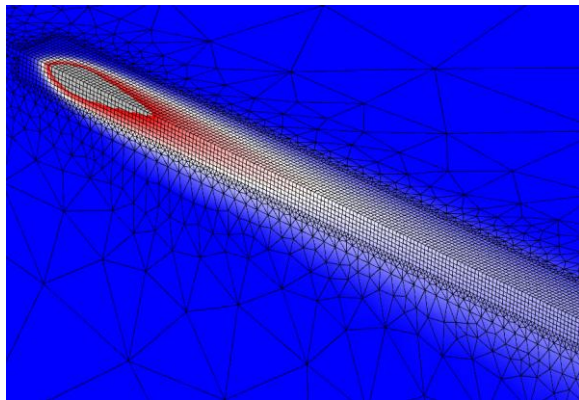
**Scan 5 ensemble:
Average MRE over all 3 variables
(global MRE 14.43%)**



**Scan 5 posterior with overlays:
Subset used for fitting (red)
Ensemble predicted subset (black edge)**

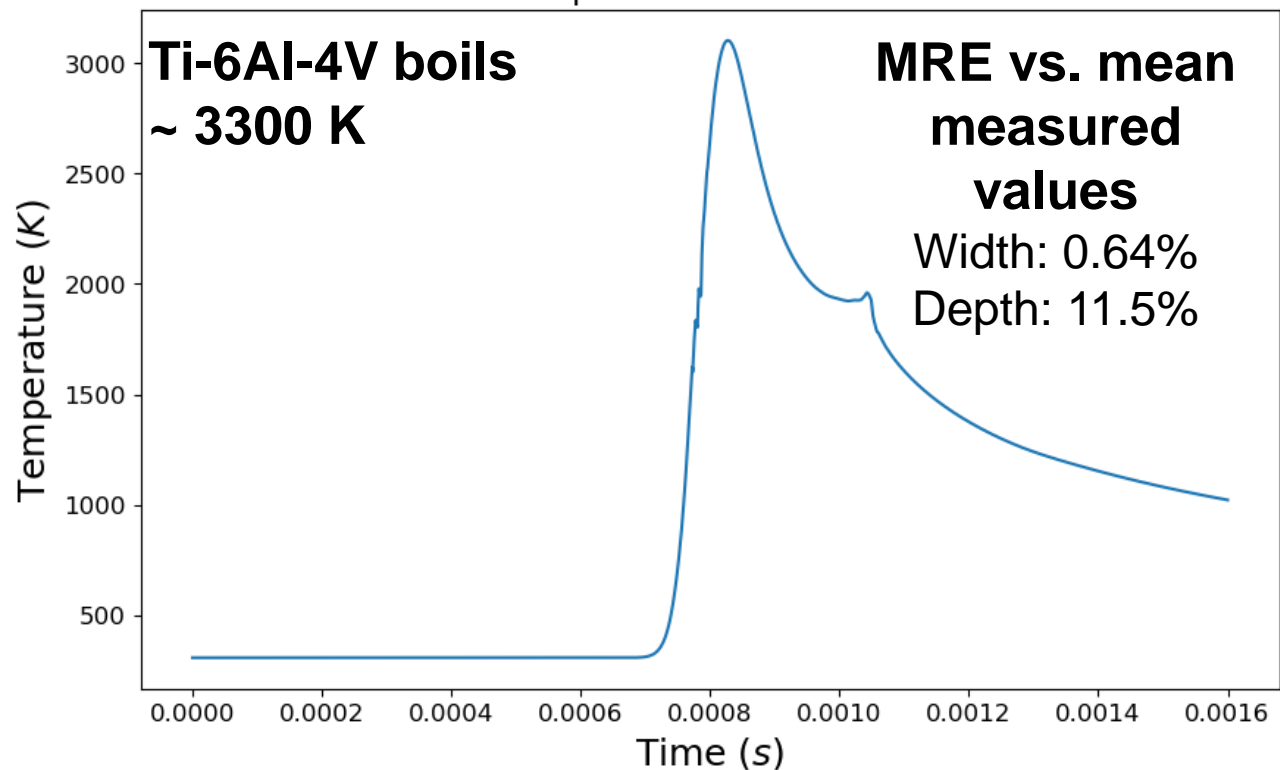


FE Model Predictions at Interpolated Validation Point



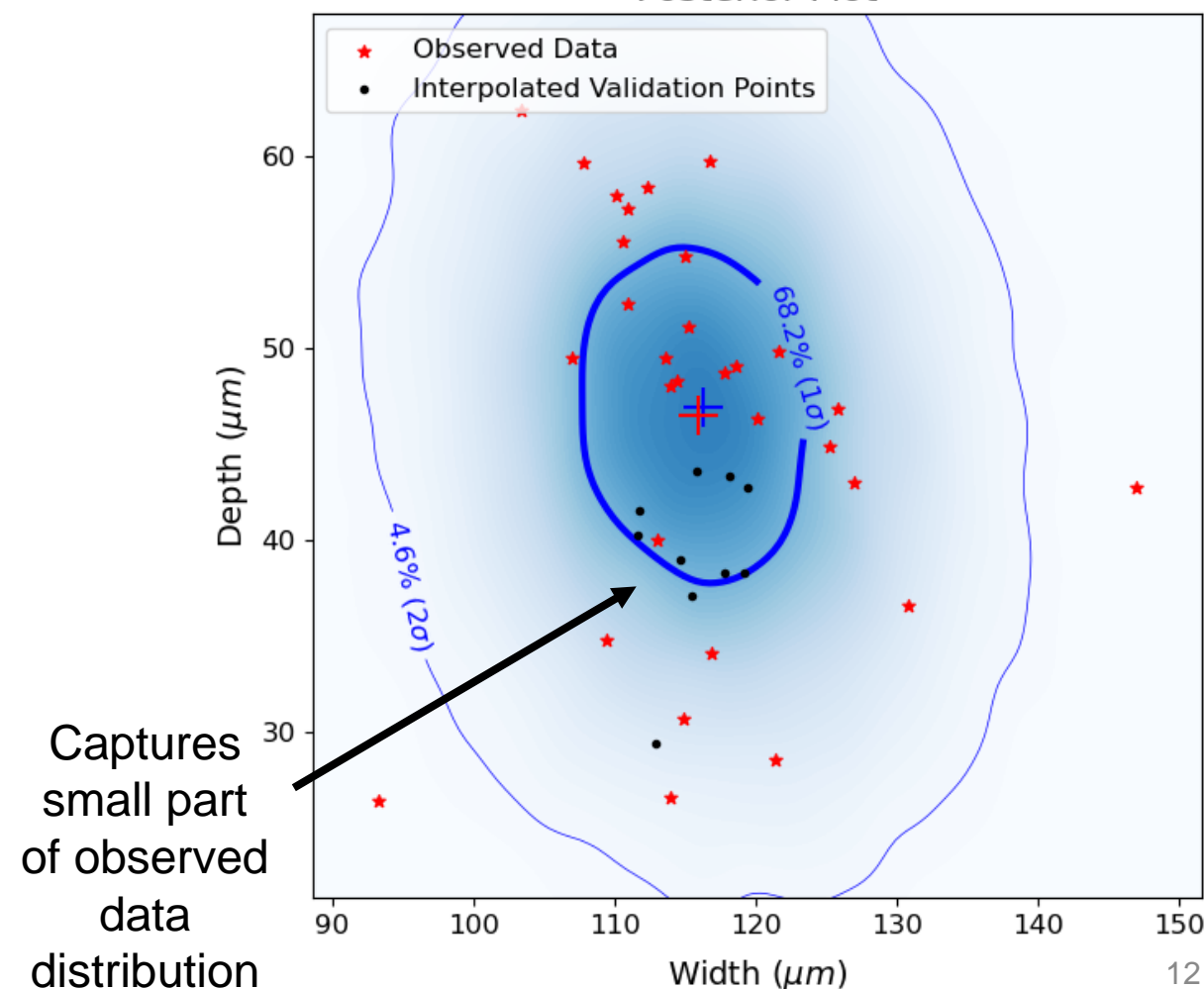
Single validation: most probable point

Mid-Point Temperature Transience at Surface



Probabilistic validation: 10 points over widest range

Posterior Plot



Concluding Remarks and Future Work



Summary

- 10 single scan tracks on bare Ti-6Al-4V plate cross sectioned to produce 300 images
- Melt pool width & depth extracted from images using CNN approach (95.2% accuracy on test set)
- Probabilistic calibration of thermal model to width & depth measurements (validation < 1.4 μm for scan 5)
- Ensemble of fits interpolator validated with scan 5
 - Most probable point vs. mean of observed values < 11.5% MRE
 - 10 points sample from posterior predict within 2σ observed values but do not capture full distribution

Future Work:

- Improve interpolator to better describe posterior distribution
 - Fits sensitive to hyper-parameter settings and posterior sub-set used for training and testing
- Further constrain calibration approach:
 - Maximum surface temperature from FE model as a calibration target
 - Target melt pool contour instead of width and depth

Acknowledgements



Project support

- NASA Transformational Tools and Technologies (TTT) Project
- NASA Langley Research Center, Structural Mechanics and Concepts Branch

CNN approach development

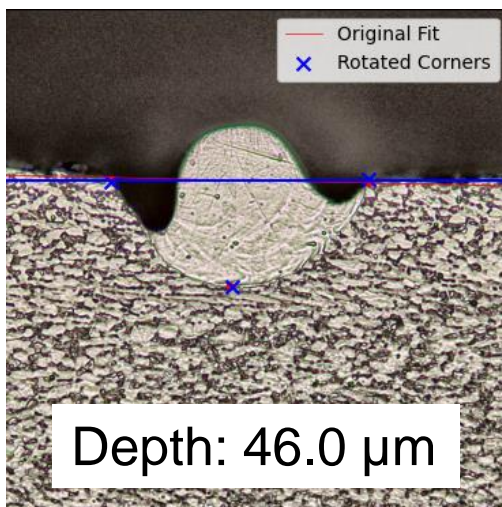
- Shannon O'Connor (Worcester Polytechnic Institute)
- S. Thomas Britt (Carnegie Mellon University)
- Hanshen Yu (Worcester Polytechnic Institute)
- Andy Ramlatchan (NASA Langley Research Center)

Physical samples and image acquisition

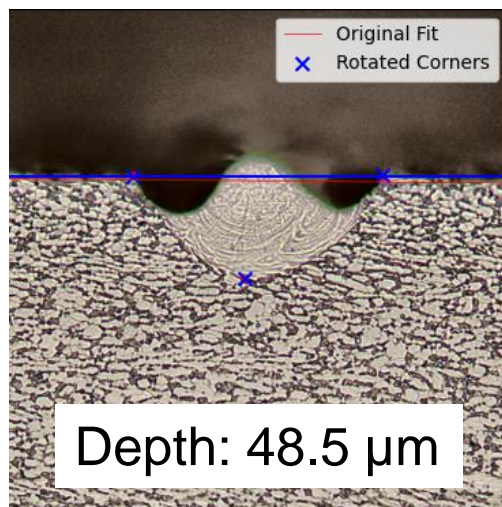
- Dr. Albert To and Seth Strayer (University of Pittsburgh)
- J. Andrew Newman and Harold Claytor (NASA Langley Research Center)

Trends in Melt Pool Depth: Example with Pad 1, Scan 6

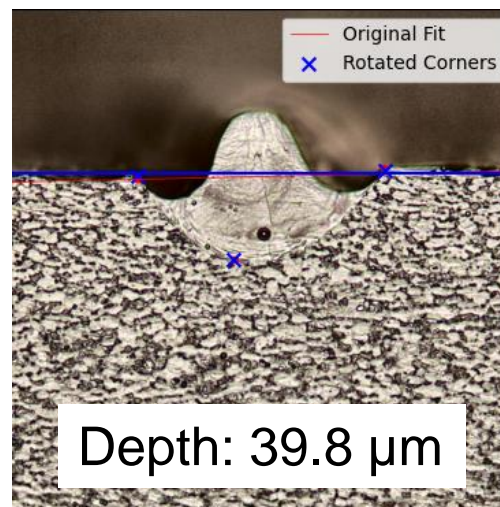
Slice 1



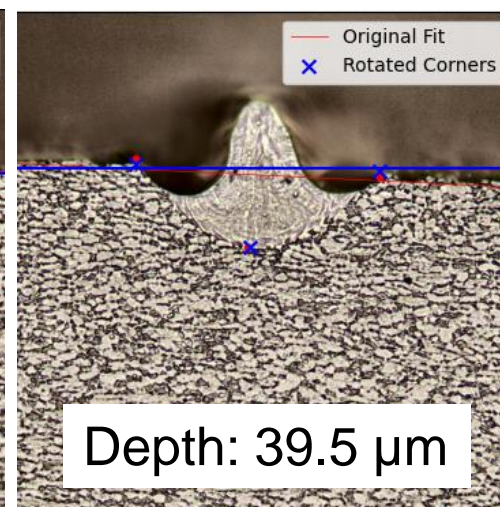
Slice 2



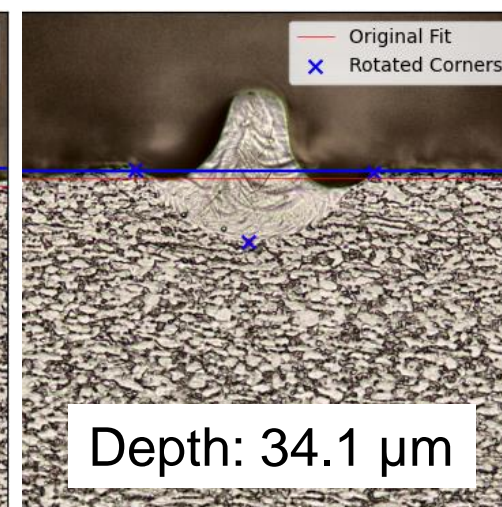
Slice 3



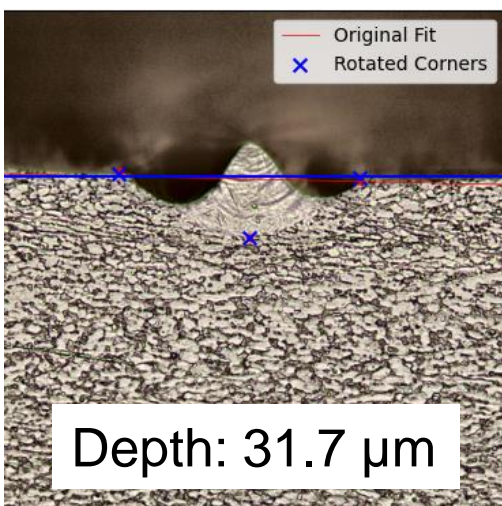
Slice 4



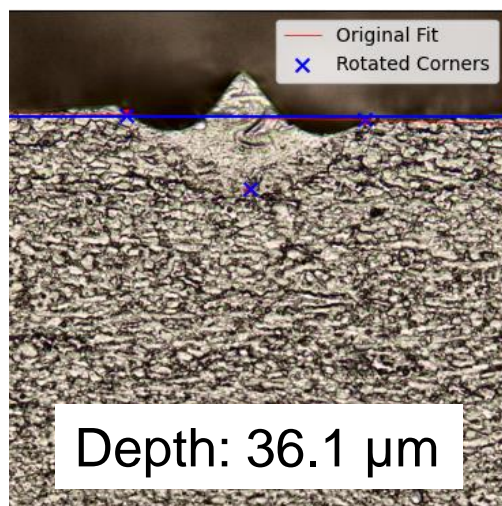
Slice 5



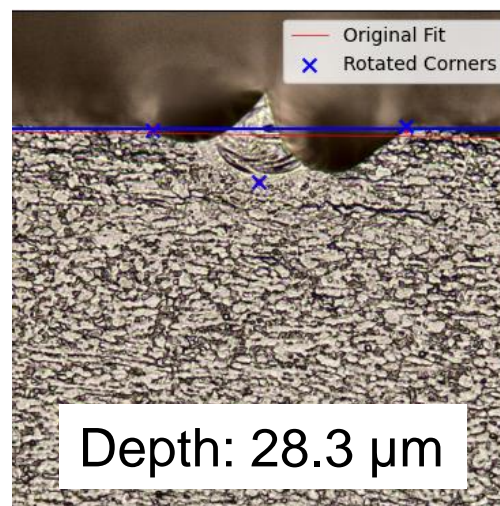
Slice 6



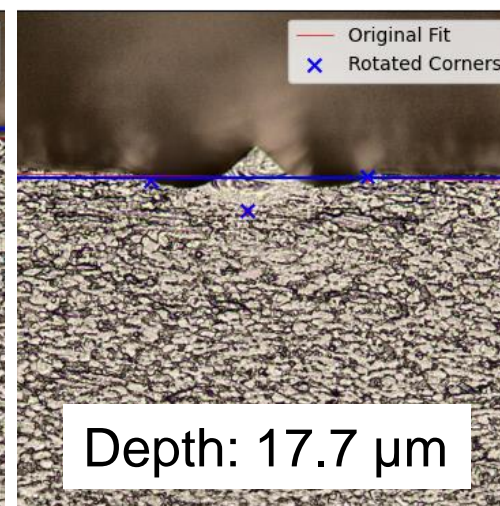
Slice 7



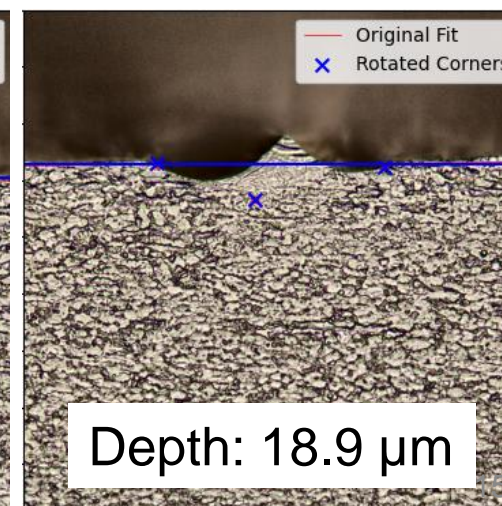
Slice 8



Slice 9



Slice 10

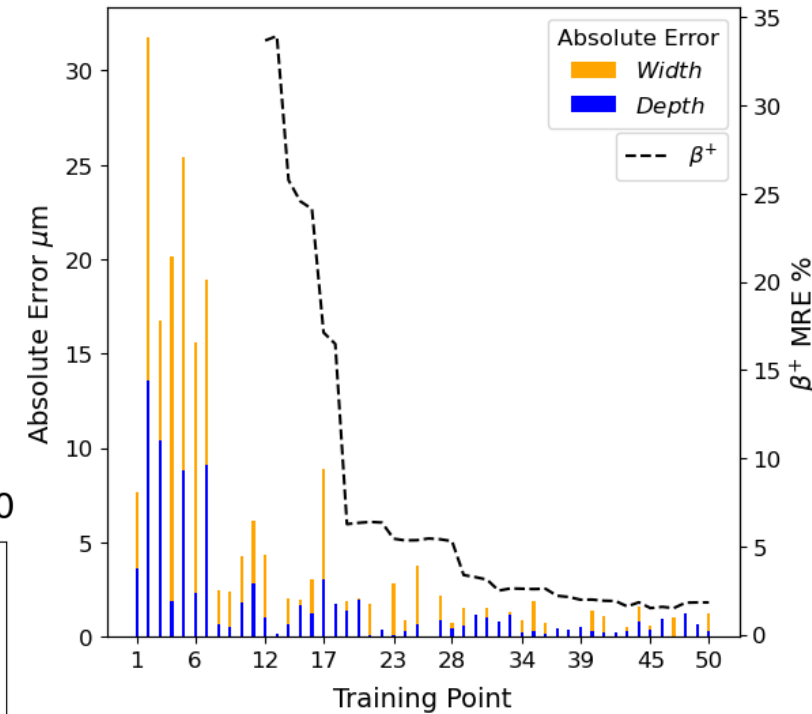
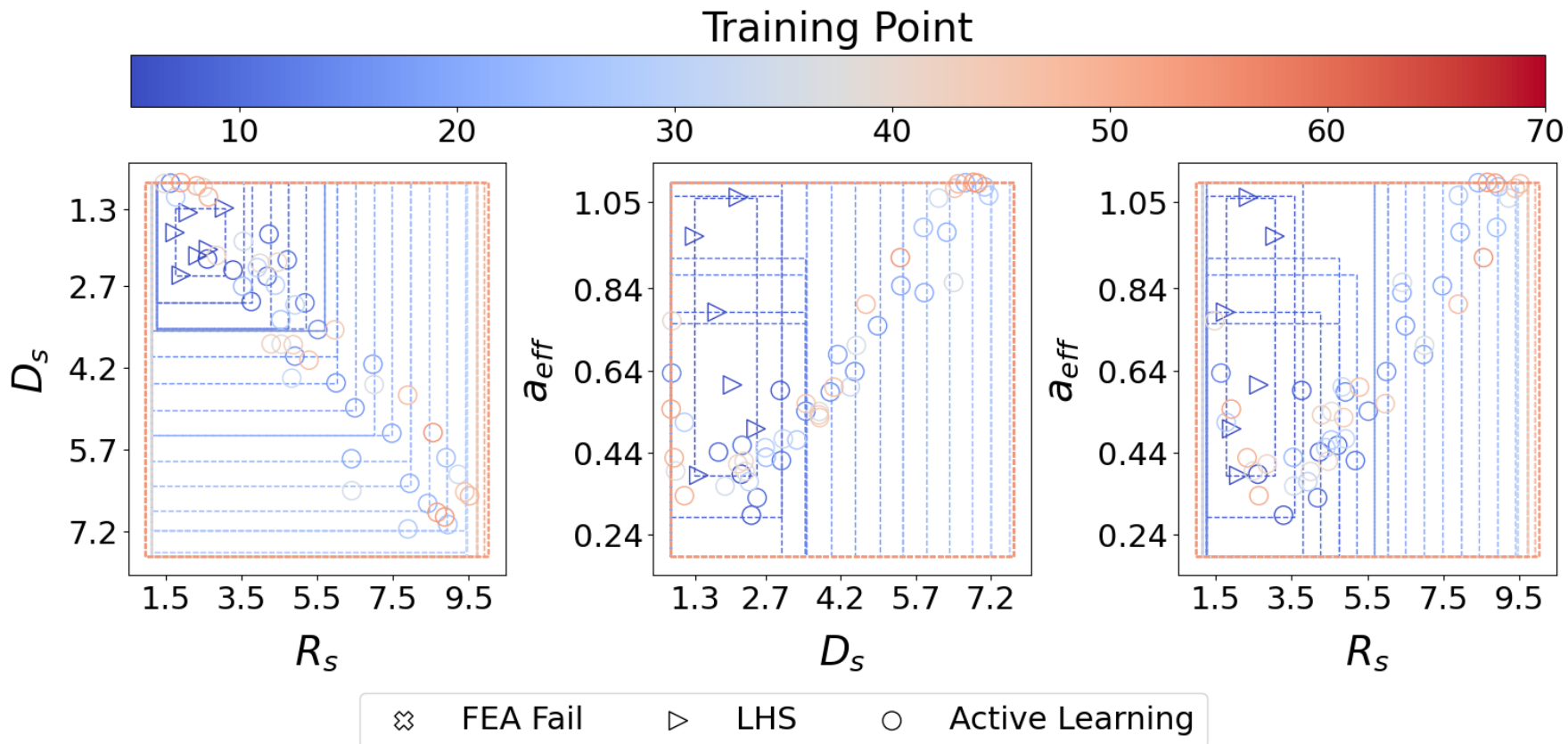


FE Model Calibration Paradigm Training (Scan 5)

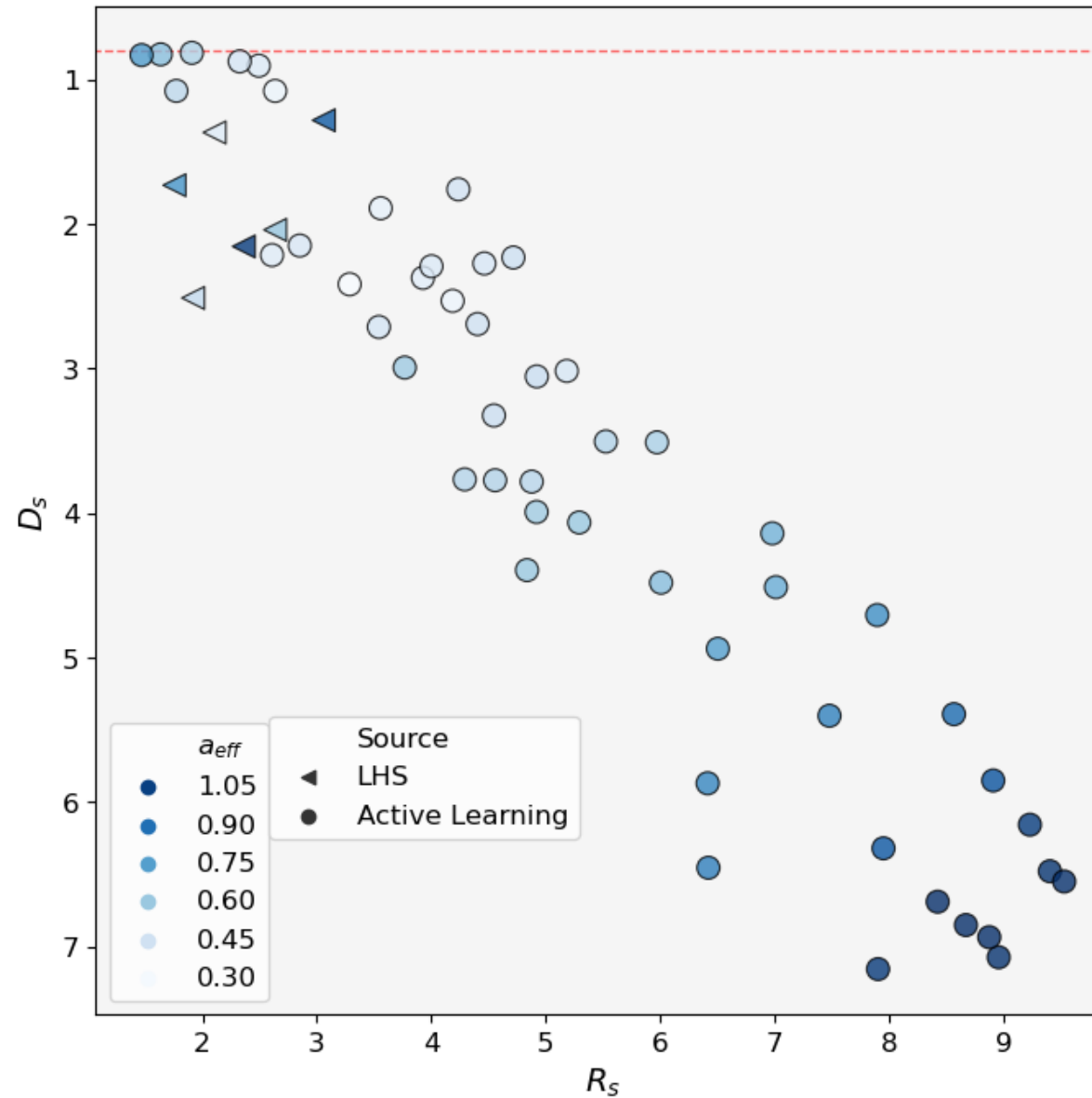


Calibration training process:

- Adaptive prior bounds automatically adjust (below) to focus active learning
 - Gaussian Process Regression (surrogate model) extrapolates to 0
 - Accelerates convergence and reduces fails
- Convergence determined by stability criterion for upper Bollinger Band® of percent mean relative error (β^+ MRE %) of iterative training points (right)



Backup: Scan 5 Training Point Distribution



Backup: Scan 5 Surrogate Contour Plot

